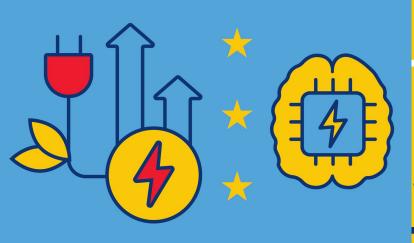
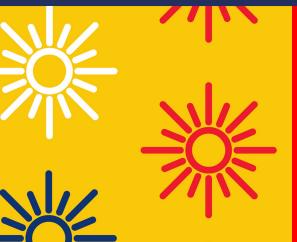


# **INCUBATENERGY LABS** 2022 DEMO DAY \*\*\* \*\* \*\* Xcel Energy\*\*







October 26 Minneapolis Minnesota





### Silvanet AI Utility Equipment Fire Detection Pilot

**Midpoint Review** October 26, 2022



Co-founder and SVP, Worldwide Sales Dryad Networks GmbH Ben@dryad.net







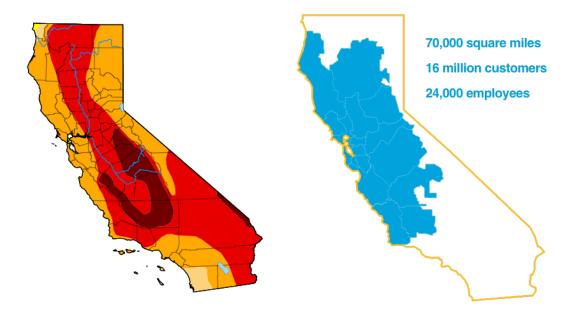
# **About the Need/Opportunity**



PG&E is committed to finding solutions to help mitigate wildfire risks from utility assets in our climate changing environment.

U.S. Drought Monitor						
Current Map	Maps	Data	Summary	About	Condition	
0 114						

#### California









# **About Dryad Silvanet**



Ultra-early detection of wildfires using Al-driven solarpowered sensors in a mesh network infrastructure



### Sensor

Solar-powered gas sensors detect wildfires even during the smoldering phase



### **Gateways**

Distributed LoRa
Gateways provide a
large-scale mesh
network infrastructure



### Monitoring

Cloud-based platform for device management, monitoring and alerting

# **Challenge: Adapting Sensors to Utility Use-Cases**



Training of the artificial intelligence (AI) sensors to recognize specific smells and avoid false-positives



### Al Training

Samples of target material (e.g. forest samples, poles, transformers) are heated up

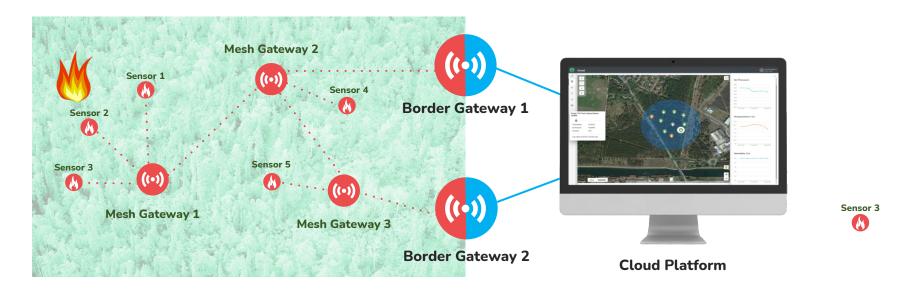
VOC / gas emitted from material

Sensors are trained to detect the specific smell

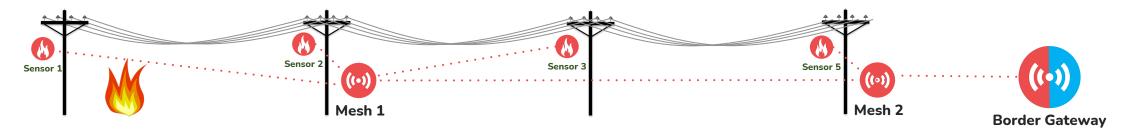
# **Challenge: Deploying Mesh Network in Linear Scenario**



Silvanet was designed to work in large-scale off-grid scenarios in the forest



Deploying in a network in a linear distribution pole-pole-pole topology



# Challenge: Radio communication range



#### **Sensor -> Gateway Communication**

Sensor id	Distance from MG	Message rate	Total nb. of messages sent	Packet loss %
2n444	510m	1 every 10m	171	0.0
2n525	510m	1 every 10m	161	0.5

Sensor id	Distance from MG	Message rate	Total nb. of messages sent	Packet loss %
2n435 <sup>up</sup>	989m	1 every 10m	171	0.5
2n437 <sup>up</sup>	989m	1 every 10m	171	0.5

### **Mesh Gateway -> Border Gateway Communication**

Gateways	Distance from MG	Total nb. of messages sent	Packet loss %
BG17, MG7	764m	480	4.1

Gateways	Distance from MG	Total nb. of messages sent	Packet loss %
BG17, MG7	1.14km	300	8.3

# **Project Scope At-a-Glance**



### Key Objective: What is being tested / proven?

- 1. Test Al sensors to detect vegetation fires; train sensors to detect wood pole fires
- 2. Test Dryad's Silvanet LoRaWAN mesh network in a linear distribution pole-pole-pole topology
- 3. Test Dryad Web & Mobile software applications to manage sensor network health and provide over-theair update to sensor detection models

### **Monthly Milestones:**

June: Project scope & schedule finalization; logistics

July: Al learning of wood samples; linear network validation; system validation and setup

August: Test planning and logistics

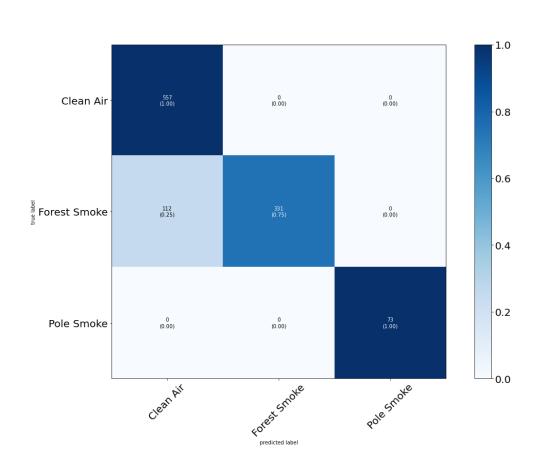
September: Testing

October: Final Project Report

# ML/Al Results with Poles (Smoke Chamber)



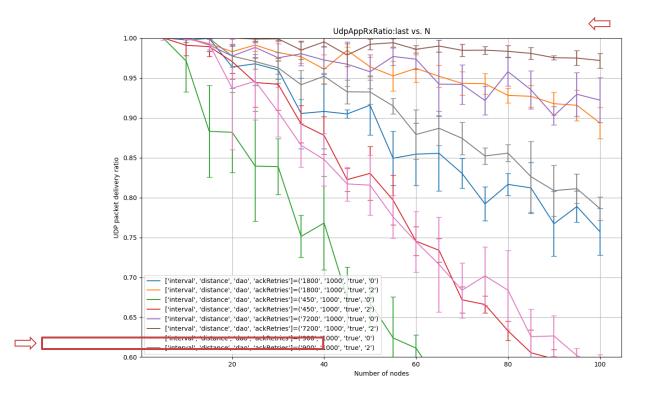
- New model that classifies smoke from poles in addition to clean air and forest smoke.
  - 100% accuracy on clean air and pole smoke (test set)
  - 74.7% accuracy on forest smoke (test set)
  - Can even identify type of pole which generated the smoke!
- Main model has 95%+ accuracy on forest smoke (test set)
  - Lower accuracy due to limited training data ( avoid class imbalance)

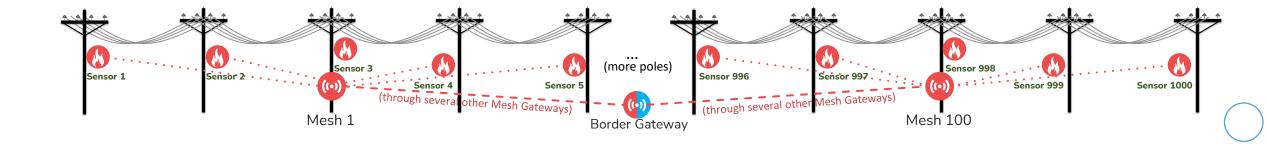


# **MESH Simulations With Pole Deployments**



- Simulated up to 1000 poles covered by one Border Gateway
  - Assuming 100m avg. pole distancing
  - 10 sensors served by each Mesh Gateway
  - 100 Mesh Gateway served by one Border Gateway
- Main result: 1000 poles can be served by one Border Gateway with
  - The target sensor reporting rate of once every two hours
  - Data accumulation is needed (a mesh message needs to convey messages from multiple sensors)
- Multiple of the above setup can be deployed





## **Cloud Enhancements**



### **Downlink Commands - CLI to UI (50 % Done)**

#### includes ..

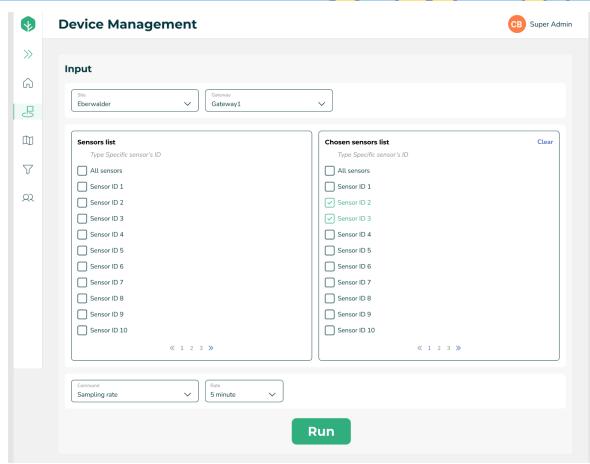
- basic commands
- composite commands
- firmware over the air updates

./all\_send\_cfg.sh ./pge\_sensors.txt -c bg22 --iaqrate IAQLP

### Multi-Classification Alerts (100 % Done)

smoke from wooden poles vs forest fire

- web application alerts (maps + central alert page)
- email alerts



## **Learnings to Date**



#### What have the team learned to date?

- MESH Topology scales well
- Machine Learning pipeline capable of handling multiple classifications

#### What are successes so far?

- MESH Topology results
- Range Test results
- Cloud platform nw handles multi-class smoke detection
- Machine Learning model capable of distinguishing in controlled environment (smoke chamber)
  - wooden pole smoke vs wildfire smoke
  - various types of wooden pole smoke

#### What are the barriers so far?

- Machine Learning model not as efficient in outdoor environments
- Wooden pole smoke vs Wildfire smoke data imbalance
- UI based automation of over-the-air update of the Machine Learning model is not fully implemented

### **Our Team**





### **Utility Representative:**

Gavin Fong, Dave Chua, Omar Mahmoud (Wildfire Risk Management)

Damian Inglin (Emerging Technology Strategy & Programs)

#### **Startup Representative:**

Carsten Brinkschulte, CEO, Dryad Networks GmbH
Cherian Mathew, Cloud Platform Lead, Dryad Networks GmbH
Ben Banerjee, SVP Worldwide Sales, Dryad Networks GmbH



































# Thank You







